

Assimilation of Sparse Continuous Ionosonde Data into Real-Time IRI

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Beacon Satellite Symposium 2016

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▪ Real-Time Assimilative Modeling with **GIRO** and **IRI**

- **GIRO** /Global Ionosphere Radio Observatory/
- **IRI** /International Reference Ionosphere/
- **NECTAR** assimilation algorithm

GIRO + IRI + NECTAR =

IRTAM

(IRI-based Real-Time Assimilative Modeling)

▪ **GAMBIT** data analysis environment for **IRTAM**

- <http://giro.uml.edu/GAMBIT>

▪ **3D Real-Time Ionosphere with IRTAM**

- Mapping anchor points of Ne profile: foF2, hmF2, B0

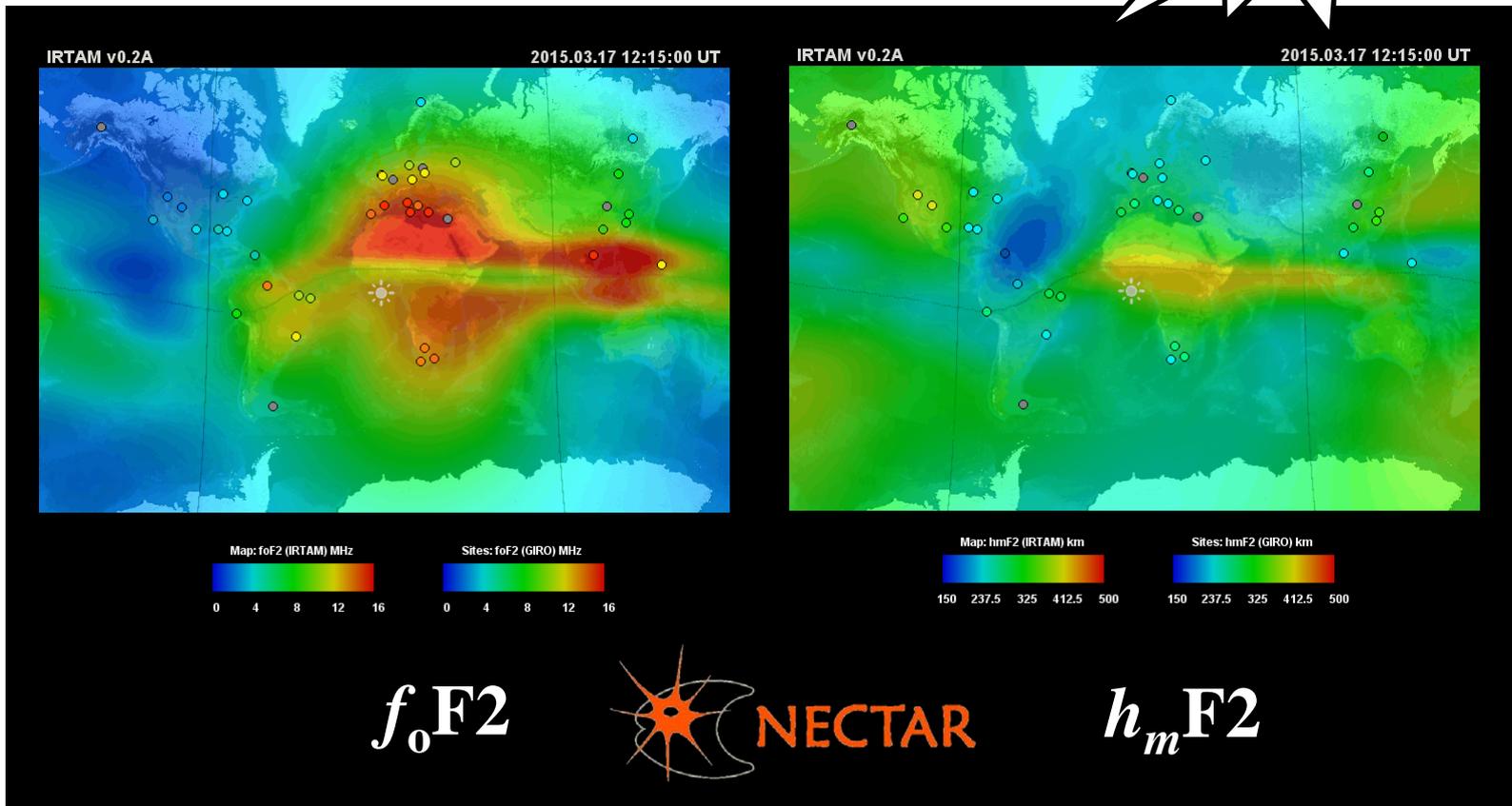
▪ **Outlook**

Real-Time IRI

24 hour history of assimilation



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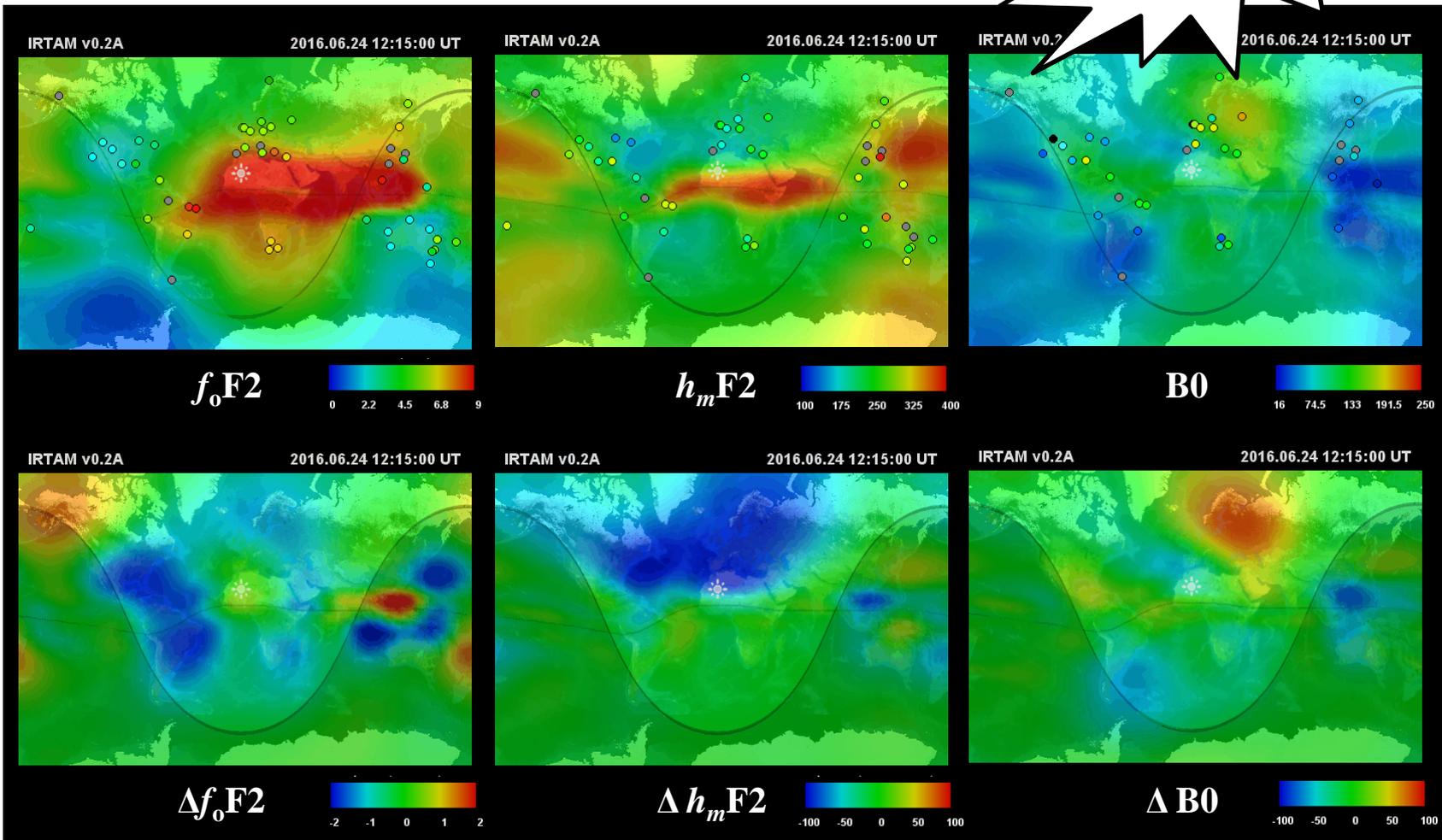


Real-Time IRI

24 hour history of assimilation



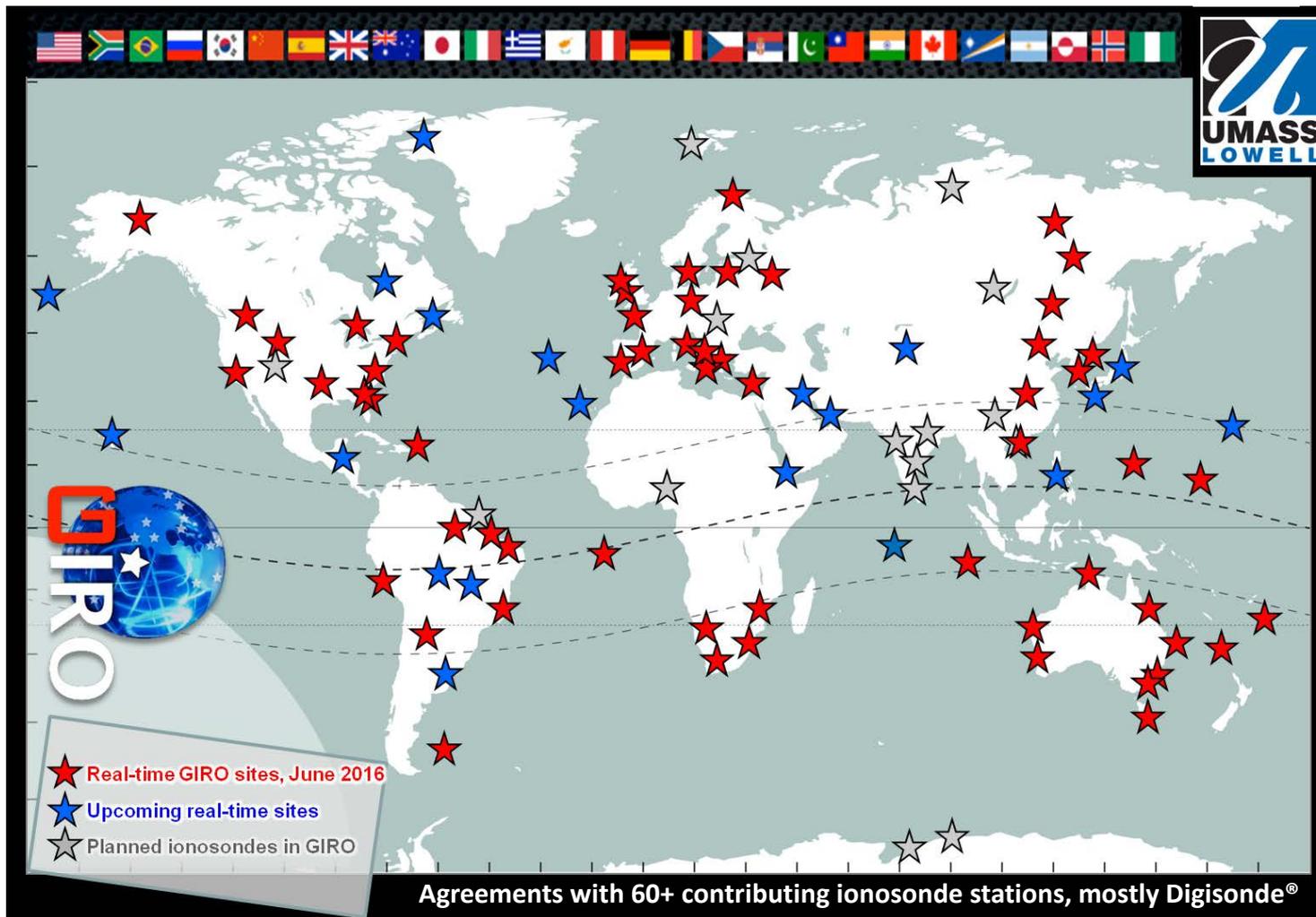
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Global Ionosphere Radio Observatory

Digital ionosondes providing real-time data to IRTAM

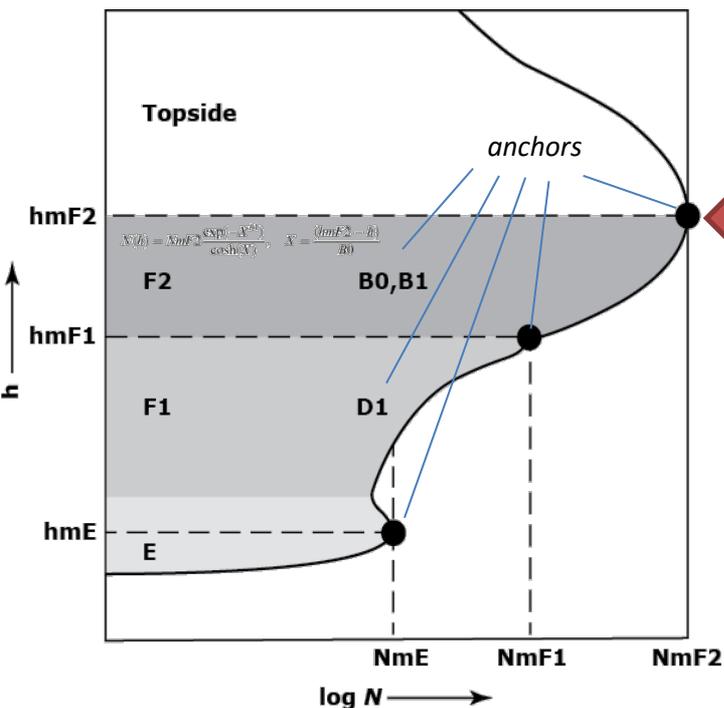
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Concept of 3D Real-Time IRI

Use 2D updated maps of Ne profile parameters

1D vertical profile of Ne



- **3D specification of Ne = 1D vertical profile with 2D maps of its anchors**
- **NmF2 and hmF2 – most important anchor that changes the whole profile**
- **B0, B1, D1 – profile shape parameters**

IRI Climatology

success:

foF2 error is 0.01 MHz ($\sigma = 0.78$ MHz)
hmF2 error is 1.51 km ($\sigma = 25$ km)
1.5+ million monthly medians
7 solar cycles, 250+ ionosondes
[\[Damboldt and Suessmann, 2011\]](#)

foF2: 200 kB worth of expansion coefficients

→ **To capture real-time SPACE WEATHER:**

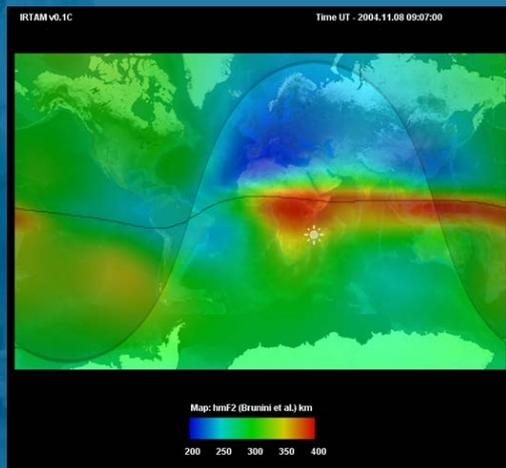
1. Keep 3D formalism of IRI
2. Use GIRO data to update 2D anchor maps

Updating IRI with GIRO data: Build weather map from monthly average climate map

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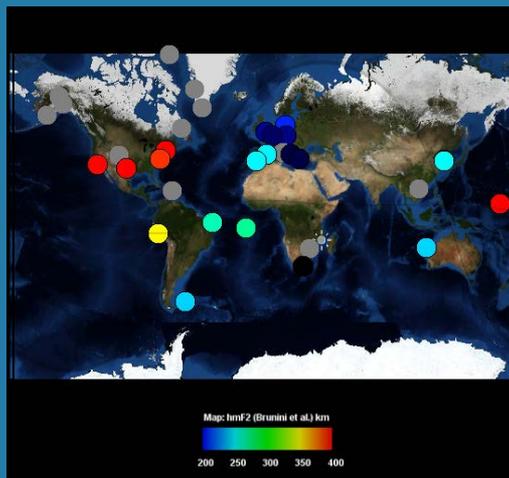
UPDATES EVERY 15 MINUTES

Example: updated hmF2 map



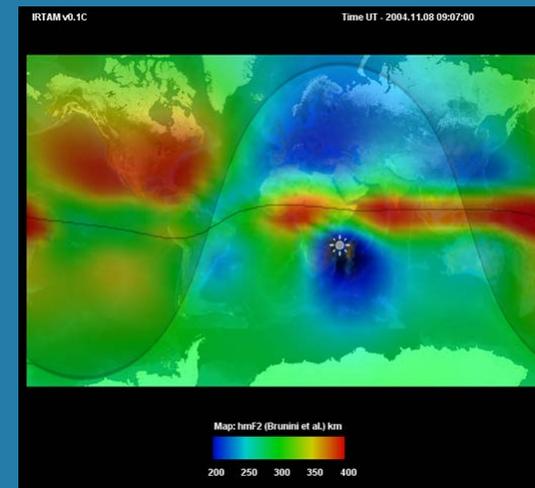
Global hmF2 Climate by IRI

+



GIRO Network Real-Time hmF2

=



Global hmF2 Weather Map

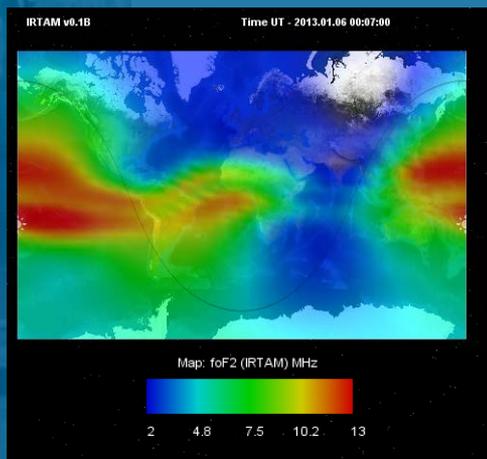
Concept credit: Real-Time IRI Task Force (2009)

IRI Concept of Mapping

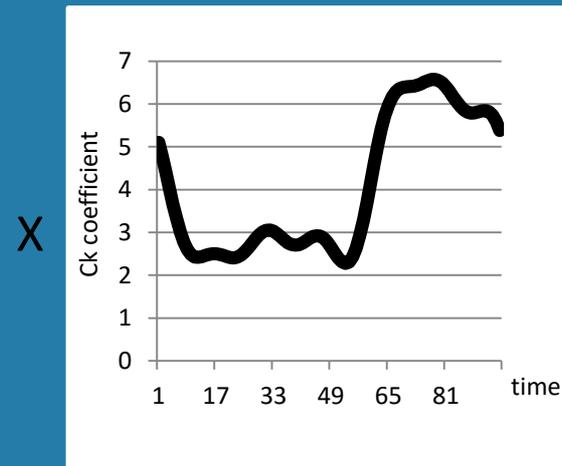
Combination of global and diurnal expansions

[Jones and Gallet, 1962-1966]

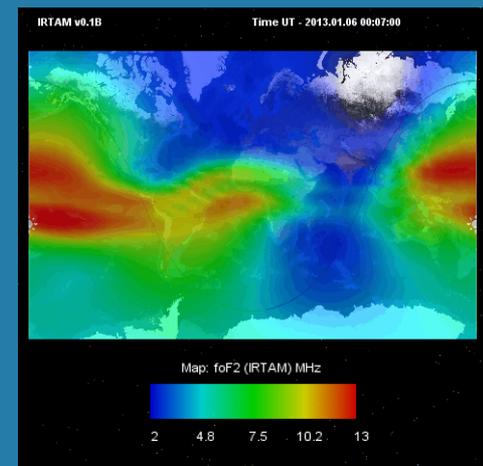
$$76 \times 13 = 988$$



One-time snapshot
76 coefficients C_k



One-day of each C_k
13 coefficients



One day in the life (DITL)
988 coefficients C_{ik}

Assimilative IRI technique:

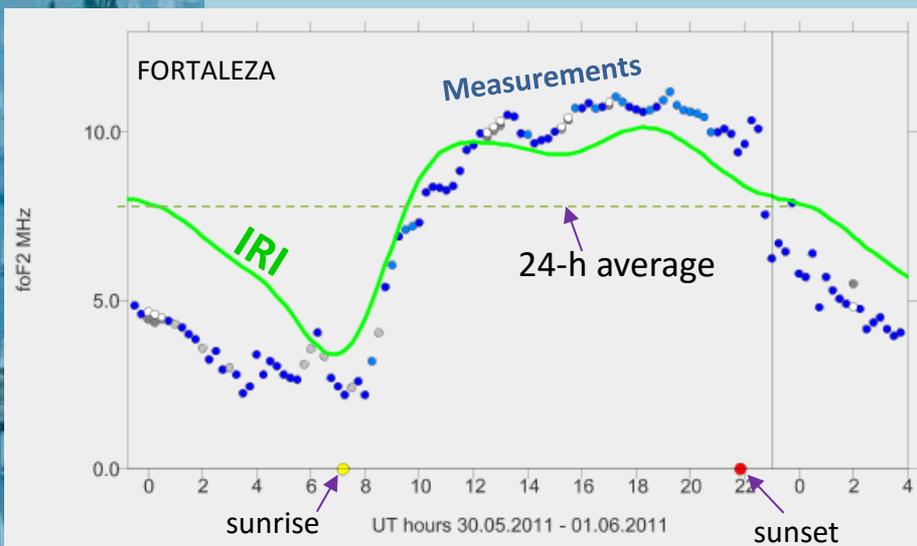
- **One “weather map” is computed using the measurements from all available GIRO ionosondes during the last 24 hrs**
 - This is a 4DDA assimilation technique with 24-hour analysis window
 - The 24-hour analysis window mitigates the effects of ARTIST autoscaling errors
- **Temporal analysis is done first for each GIRO site**
 - using the 96 measurements each station makes during 24 hrs
- **Spatial analysis is done second**
 - Each diurnal harmonic is expanded individually
 - Potential for detecting and capturing planetary scale processes (low-order diurnal harmonics)

I. Temporal analysis: IRI vs IRTAM

single-location 24-hour representation

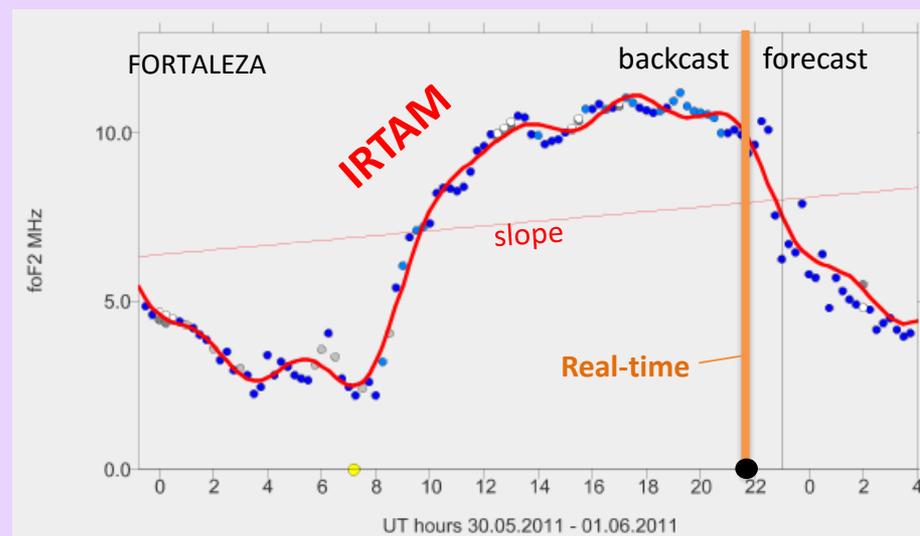
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IRI: average + variations
(13 coefficients for harmonic expansion)



No slope in 24-hour climate prediction
(loops indefinitely)

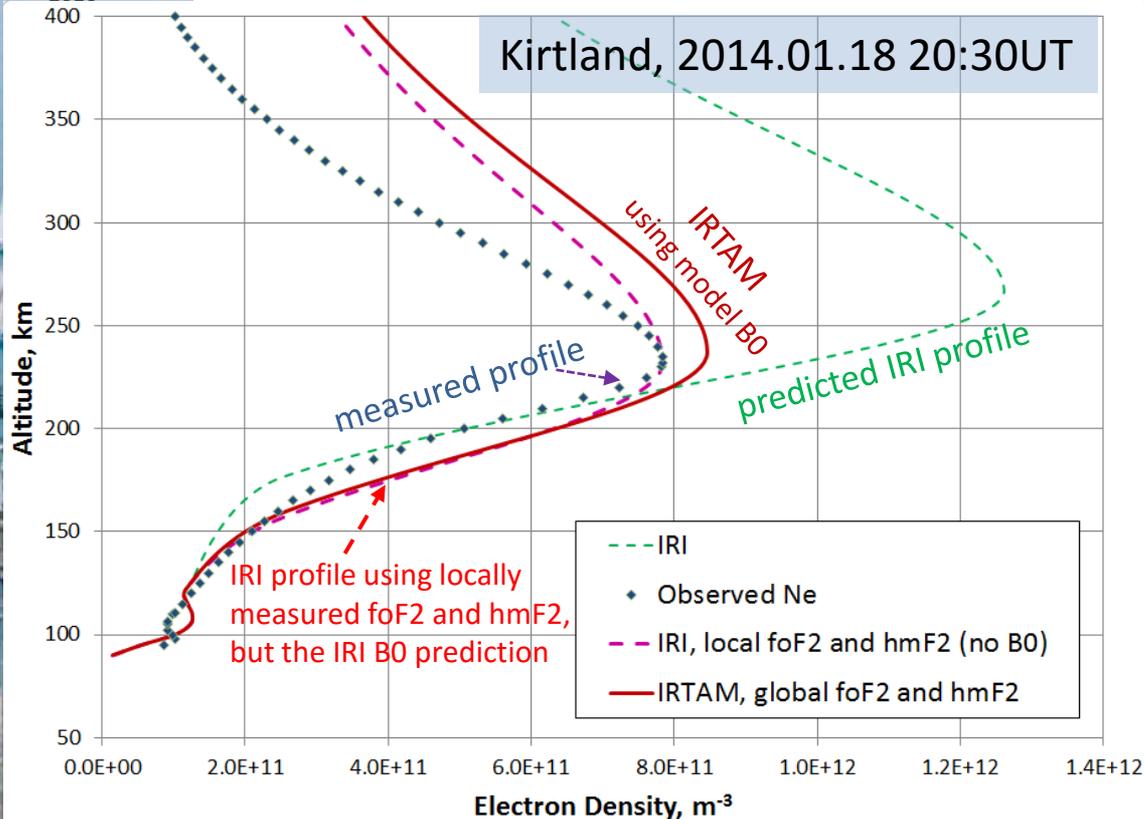
IRTAM: average + slope + variation
(14 coefficients for detrending and harmonic expansion)



Slope in 24-hour weather timeline
(no need for smooth return to beginning 24 hrs ago)

Importance of B0 assimilation

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- The model profiles on the left use the IRI model B0 value, not the measured or assimilated B0.
 - Clearly, the bottomside profile is too thick!
 - Using assimilated B0 makes bottomside thinner (not shown)

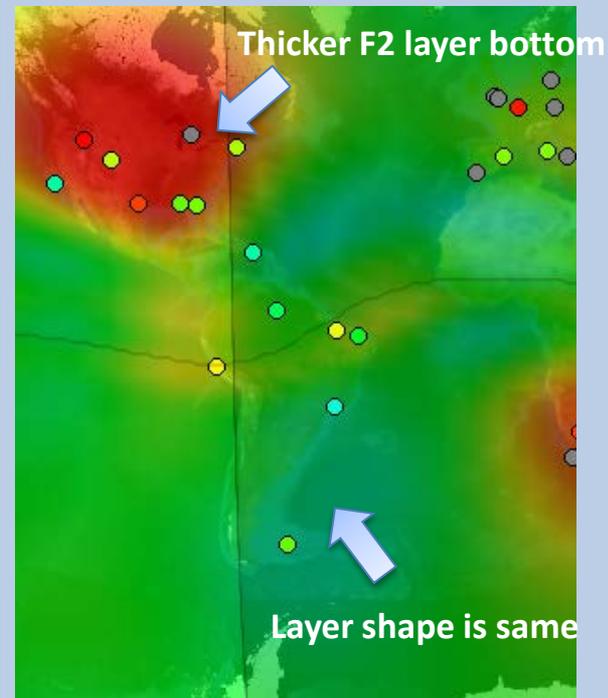
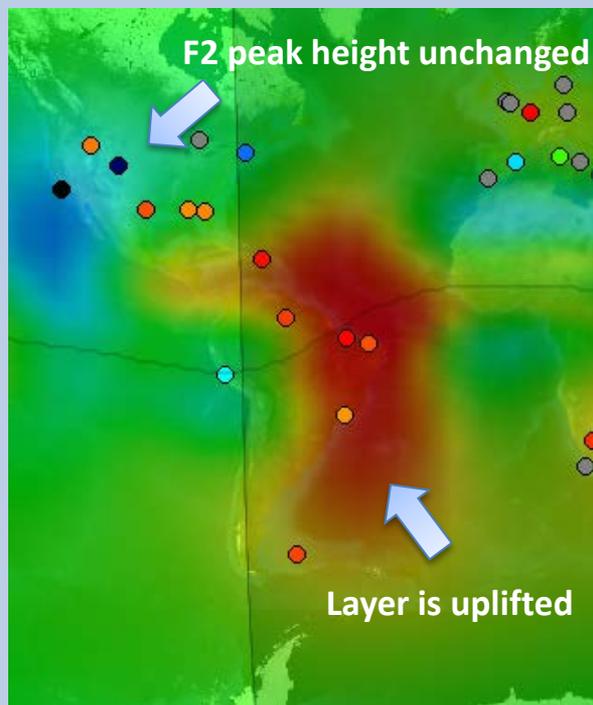
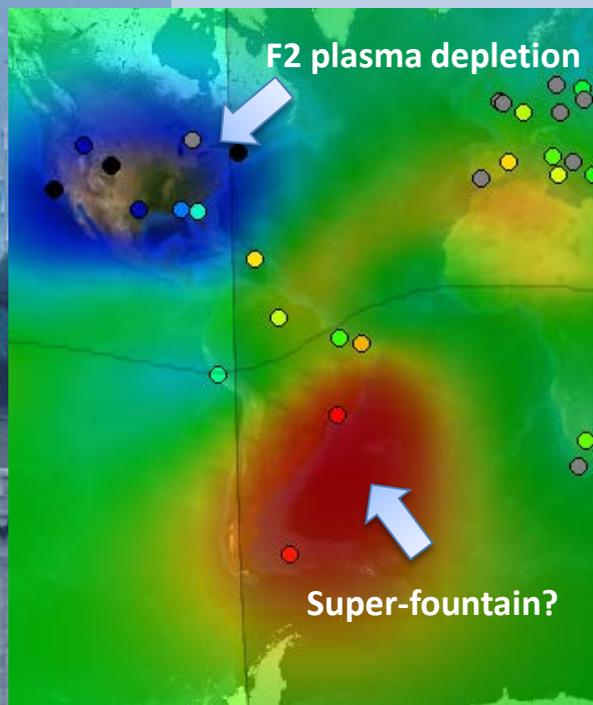
2. Spatial analysis in IRTAM

- **2A. Data interpolation between GIRO sites**
 - Interpolation of *corrections* to IRI background determined by comparing IRI predictions with GIRO observations
 - Interpolation of coefficients to *diurnal harmonic* expansion
 - Longer covariance radii for low-order harmonics
 - NECTAR interpolator based on Hopfield neural network
 - Multi-cell iterative optimization for interpolation smoothness via neuron computations with fading synoptic weights
- **2B. IRTAM Spatial representation of full grid:**
 - Update the 76 ITU-R coefficients in the Jones-Gallet formalism (which is optimized for the Appleton anomaly representation)
 - Algorithm for least-square-error fit of 76th order

Summary: IRTAM + GIRO Capability

Example of March 17, 2015 substorm, very peculiar

DEVIATION FROM EXPECTED QUIET-TIME BEHAVIOR



$\Delta foF2$

$\Delta hmF2$

$\Delta B0$

GAMBIT Database and Explorer

Public access to IRTAM retrospective and real-time results

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GAMBIT Homepage

giro.uml.edu/GAMBIT/

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UMASS LOWELL

GAMBIT

GLOBAL ASSIMILATIVE MODEL OF BOTTOMSIDE IONOSPHERIC TIMELINES

Map: hmF2 (IRTAM-Brunini) km

Sites: hmF2 (GIRO-Brunini) km

Early release [User Version 0.1C download](#) (64-bit Java 7 or higher is required)
Early release [GAMBIT Explorer User Guide 0.1C](#)

Last updated: April 16, 2015

<http://giro.uml.edu/GAMBIT>

Complementing GIRO with GNSS TEC

Concept was presented separately at Monday's Session I

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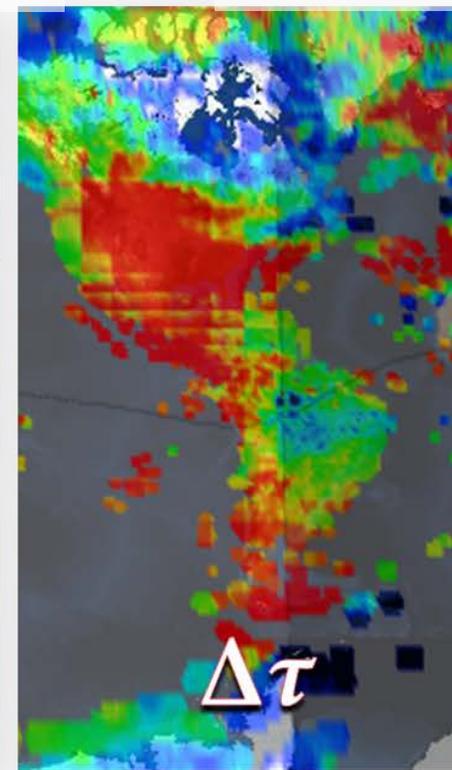
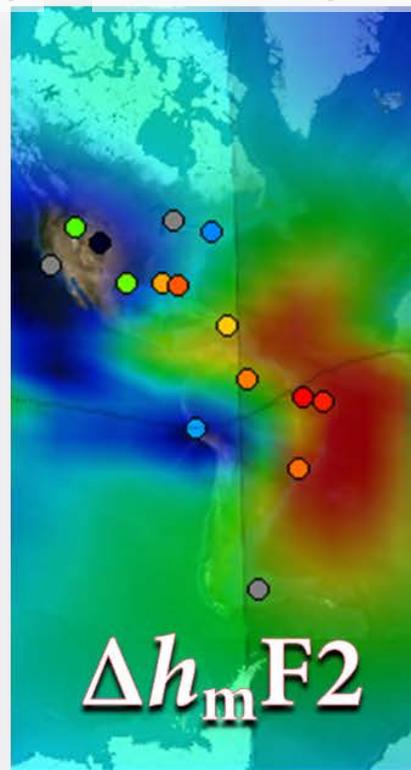
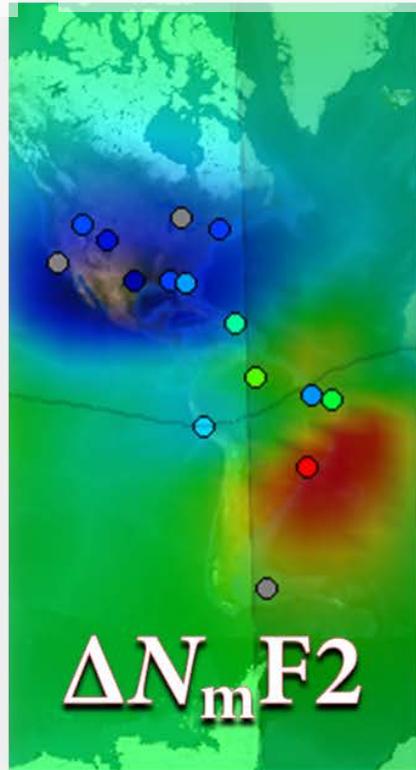
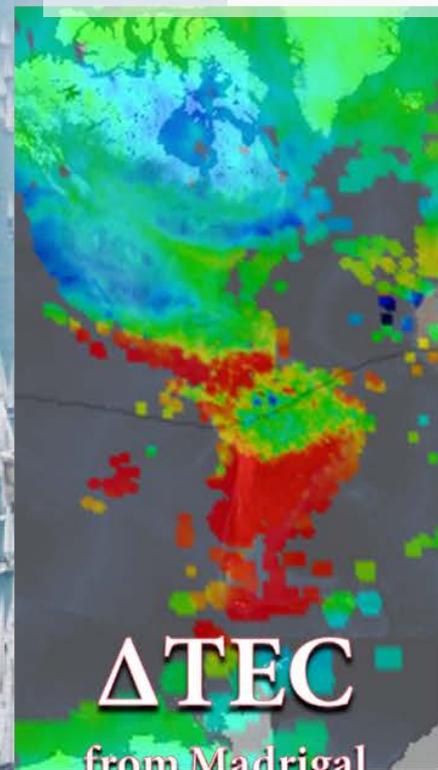
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Total Electron Content

Peak Electron Density

Peak Density Height

Slab Thickness



Deviation from expected quiet-time behavior

Red: larger than model

Blue: smaller than model

- **Cooperative real-time nowcast using GIRO profile data and GNSSTEC**
 - Implementation is imminent
 - Latency of GIRO data: 7 min, working to reduce to < 3 min
 - Current objective at GIRO: 3D profile specification
 - Current objective at IGS: Service integration with Services at Lowell GIRO Data Center and UWM IGS RTS node
- **Applications to space weather research and practice**
 - Ratio of slab-thickness τ to bottomside half-thickness $B0$ is measure of topside electron content.
- **GAMBIT environment in open source domain for data access and visualization**
 - GAMBIT Consortium is open for membership